

HOW TO INTEGRATE NFC FRONTENDS IN LINUX

WEBINAR SERIES: NFC SOFTWARE INTEGRATION

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NFC READERS
NFC EVERYWHERE
14/09/2017



PUBLIC



SECURE CONNECTIONS
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Agenda

NFC software integration webinar series

Session I, [14th September](#)

How to integrate NFC frontends in Linux.

Session II, [28th September](#)

How to integrate NFC controllers in Linux.

Session III, [11th October](#)

How to port the NFC Reader Library to K64F.



Agenda

NFC software integration webinar series

Session I, [14th September](#)

How to integrate NFC frontends in Linux.

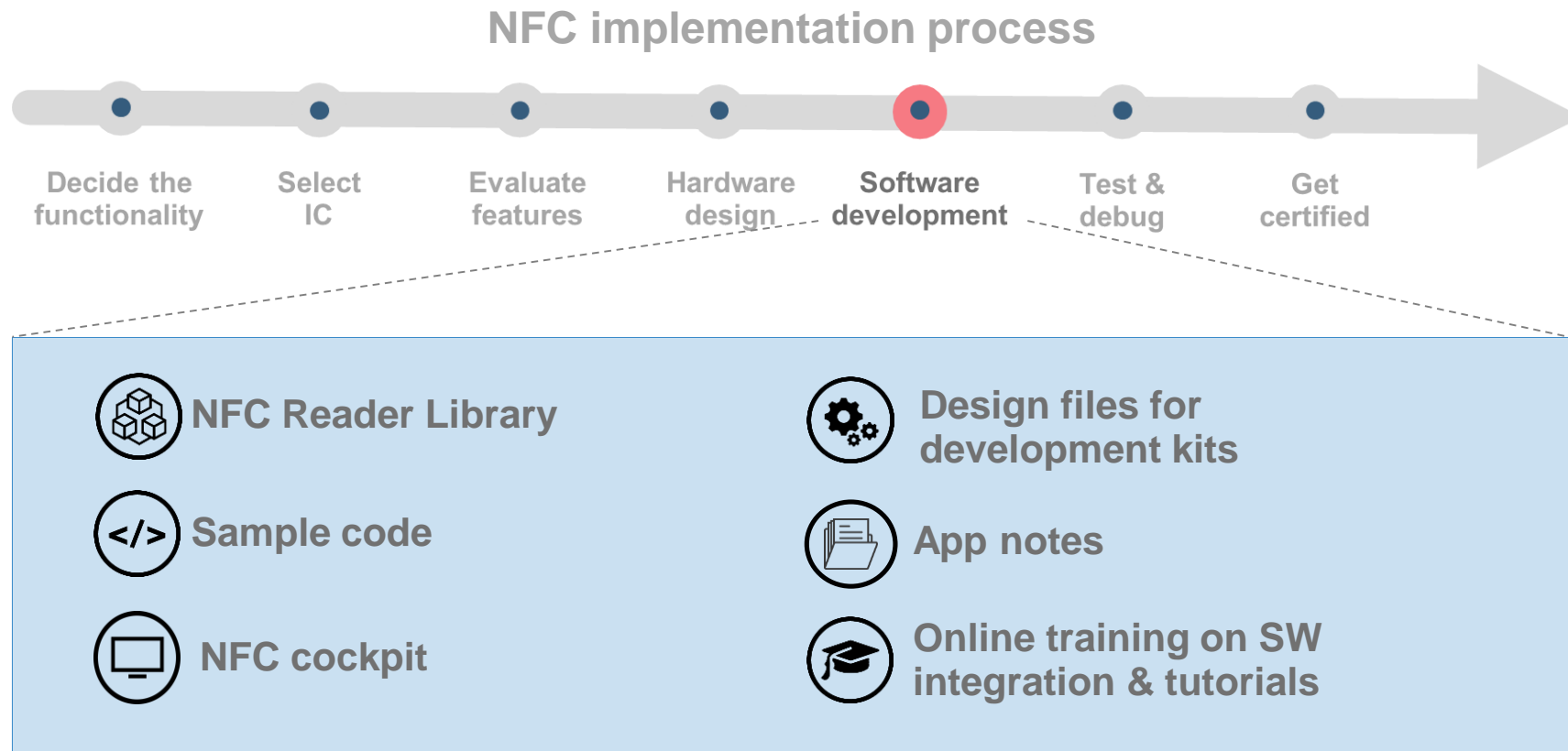
- ▶ NFC readers software development design-in support.
- ▶ NFC Frontend concept.
- ▶ Linux OS architecture & NFC Reader Library integration in Linux.
- ▶ Host interface latency analysis in Linux.
- ▶ Wrap up & Q&A.



NFC readers software development design-in support

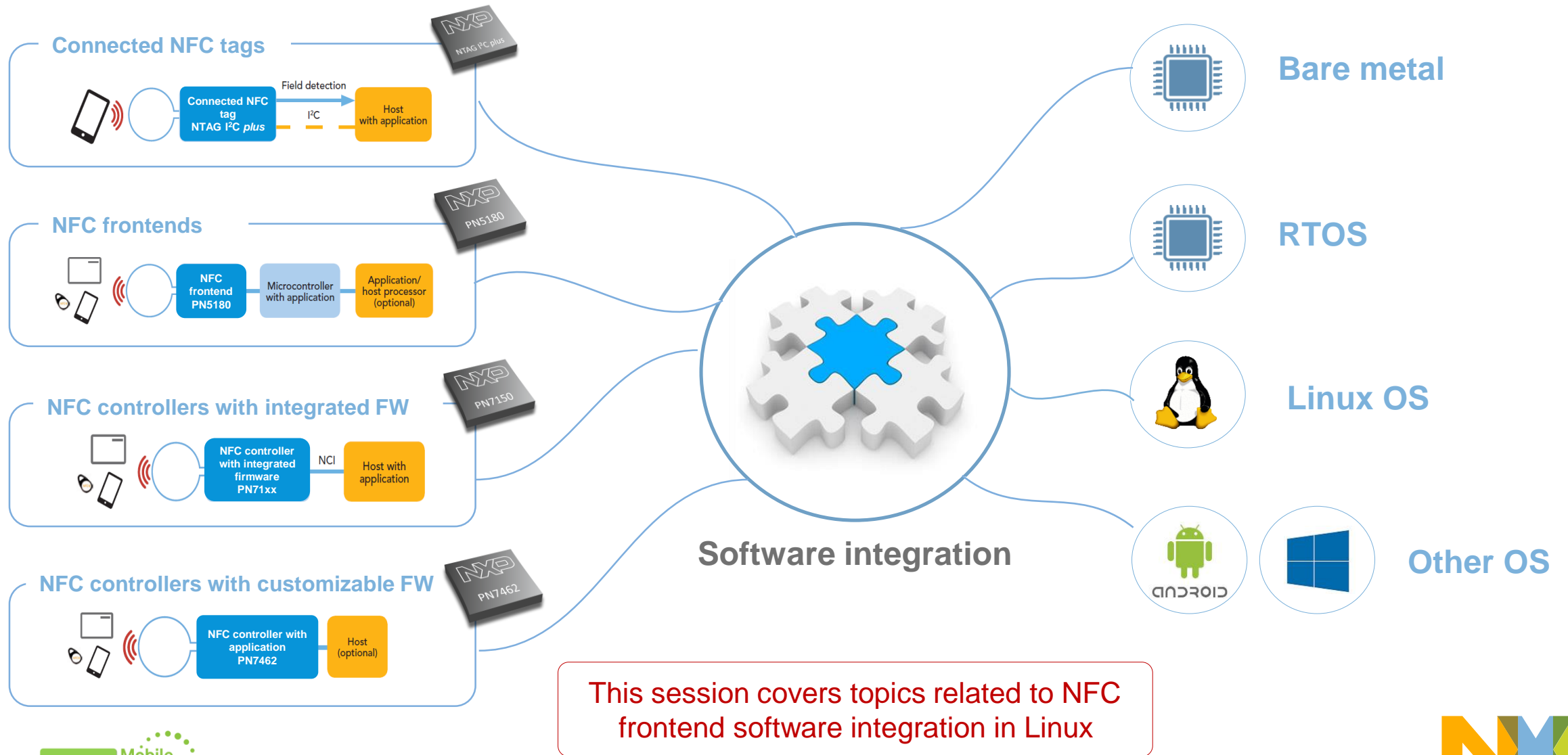


NXP's software development support



You can re-use design of NXP development boards and sample code examples to speed up your SW development tasks.

NXP software support for integration into any platform

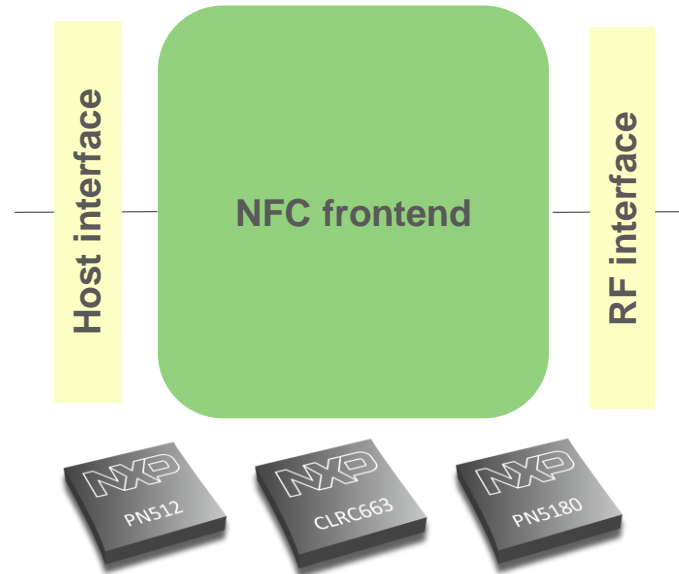


NFC Frontend concept

NFC frontend offers a host interface and a contactless interface

Host interface

- This register interface is a low level access to the contactless interface providing full access to this IP.
- This could be a direct CLIF-mapped interface (CLRC663, PN512) or a software emulated register interface (PN5180).
- The host controller uses the register access to the contactless interface:
 - to configure RF framing and signaling .
 - to finally transfer the RF digital protocol based blocks to/from a counterpart.



RF interface

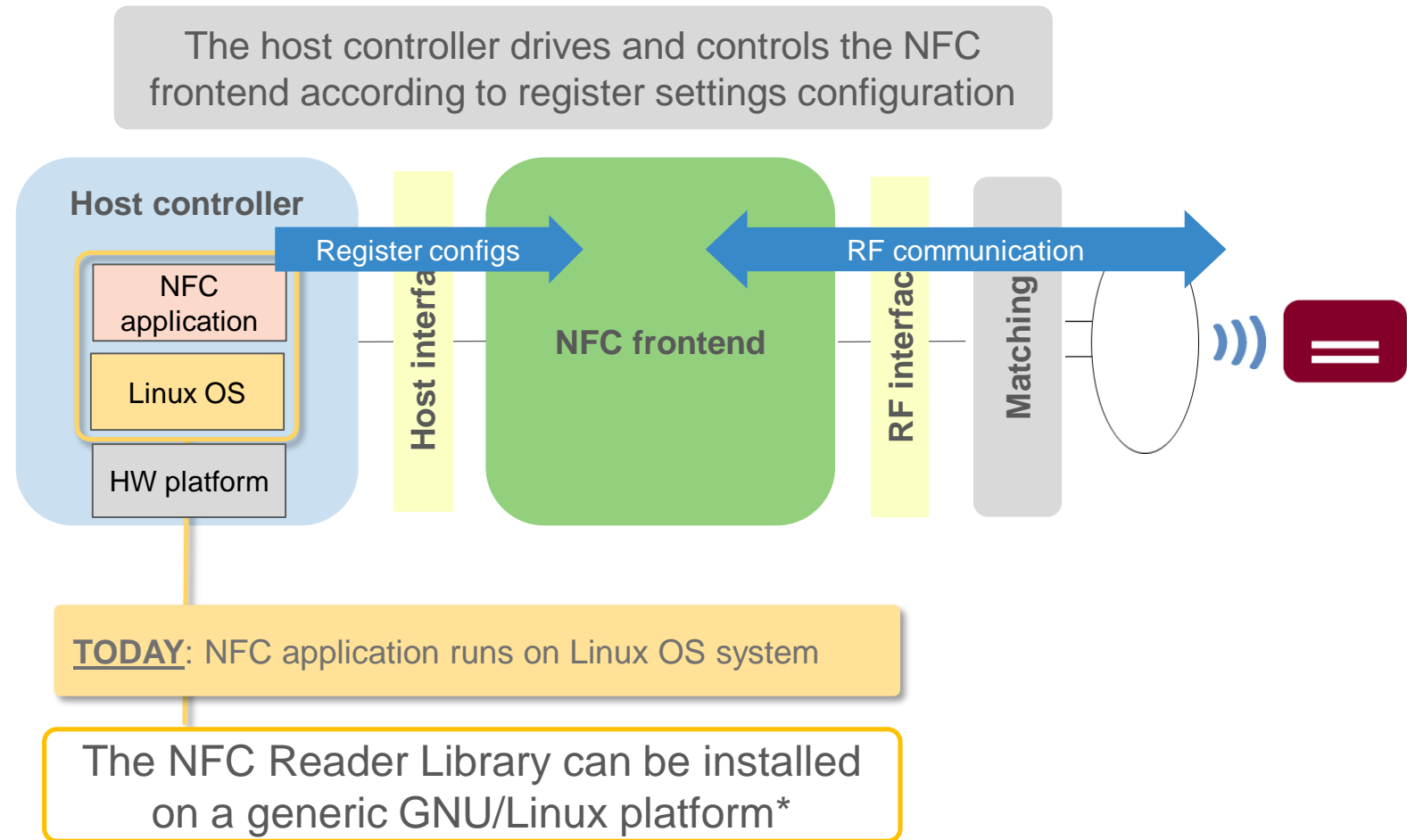
- An NFC frontend is an RF transceiver enabling the contactless communication.
- It deals with the signal modulation and handles the data transmission through the RF interface.
- The NFC frontend needs to be selected according to application requirements:
 - RF performance
 - RF protocols
 - NFC modes of operation
 - Host interfaces
 - Power consumption
 - Device to interact with
 - Others...

NFC frontends expose a 'register interface' towards the host controller through the host interface

NFC frontend is controlled by the external host controller SW

Host controller

- Contains the software implementing the application logic
- The RF digital protocols are implemented on the host controller
- The host controller platform needs to be selected according to system requirements:
 - Memory requirements
 - Clock frequency
 - MCU architecture
 - Host interfaces
 - Power consumption
 - GPIOs and other peripherals

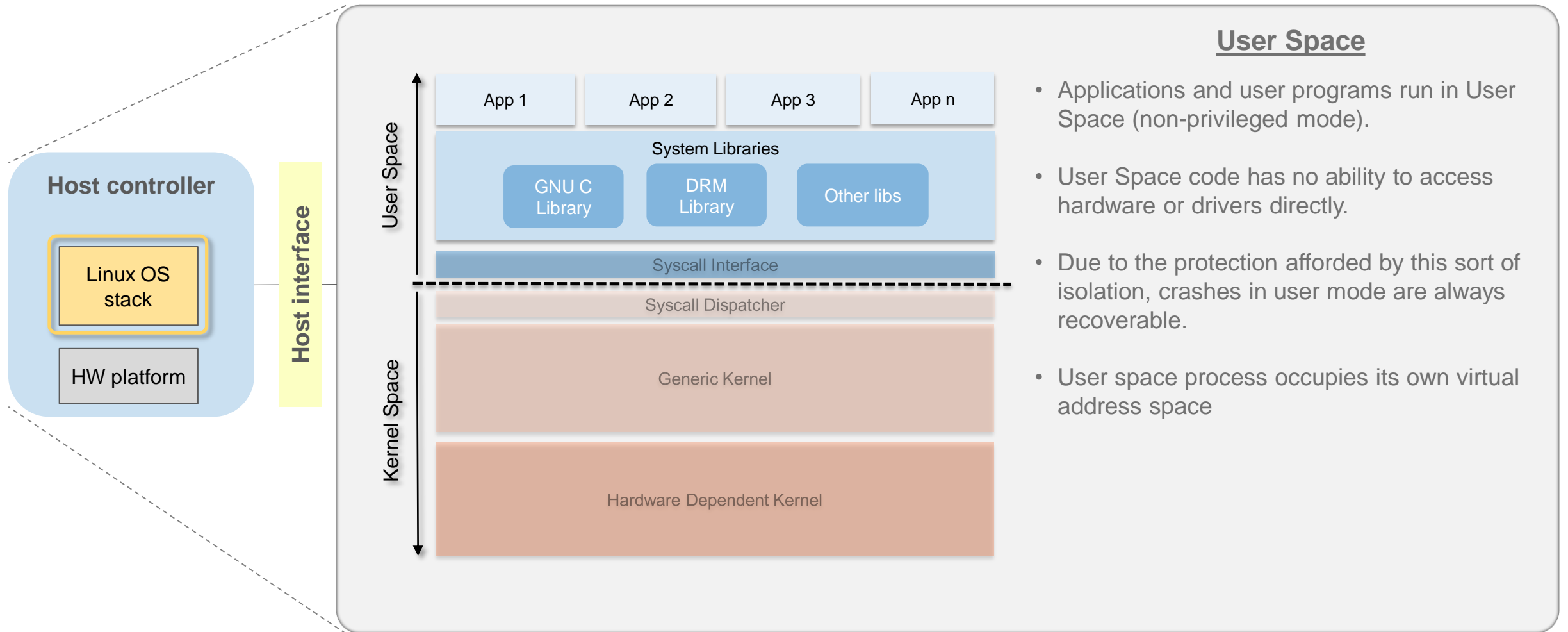


*Support on Raspberry Pi platform provided as reference.

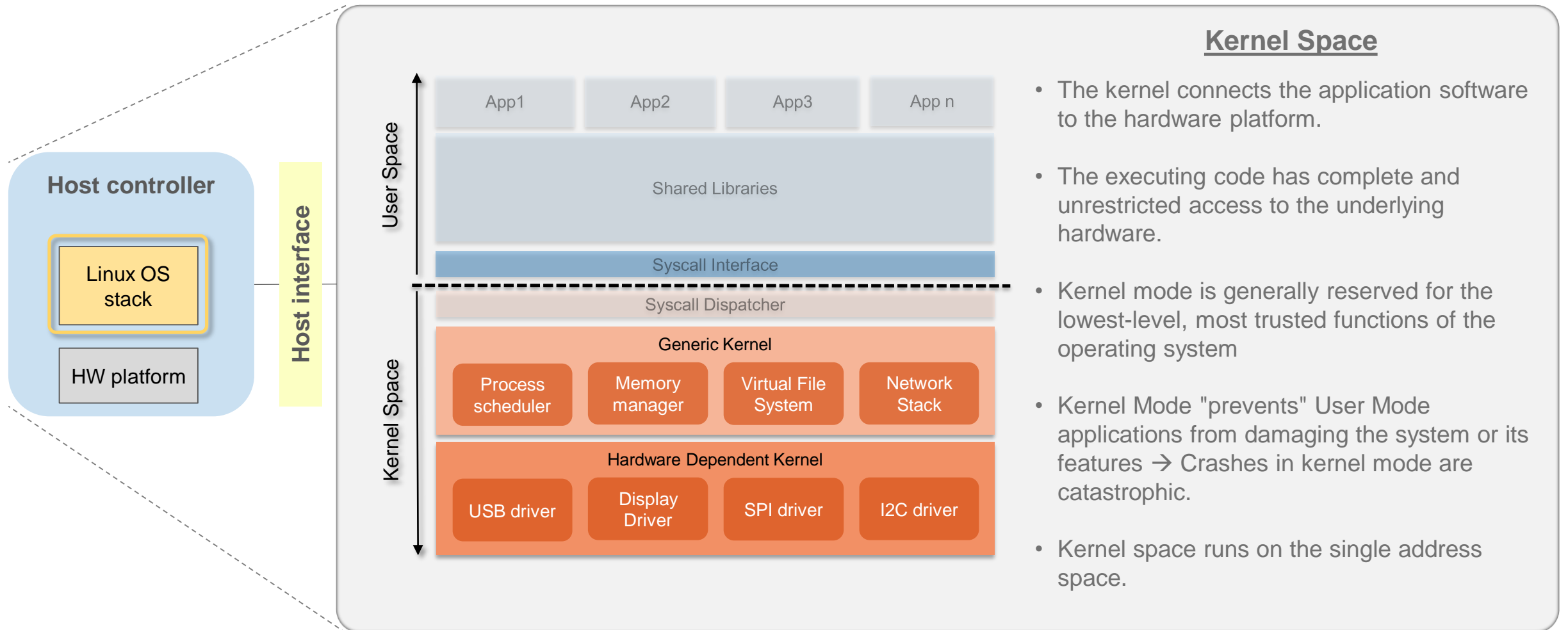
Linux OS architecture



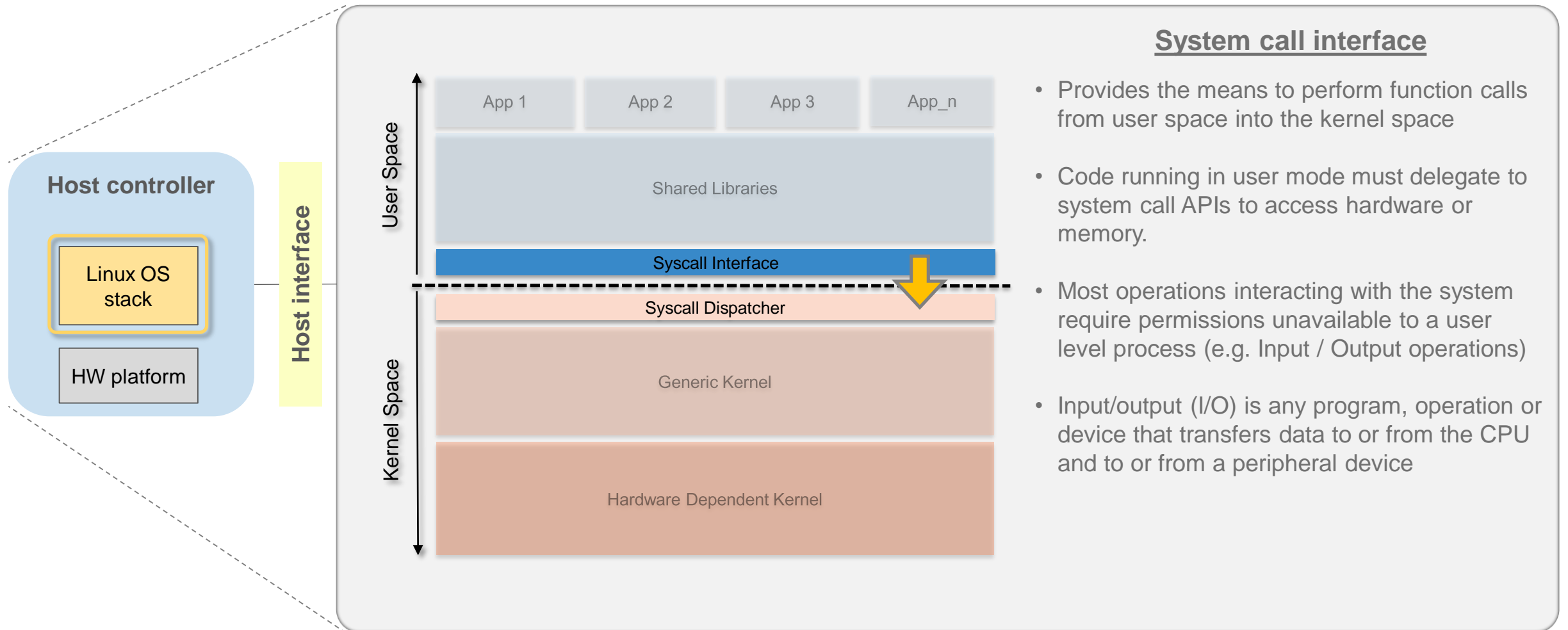
Host controller SW: Linux OS architecture - User space



Host controller SW: Linux OS architecture - Kernel space



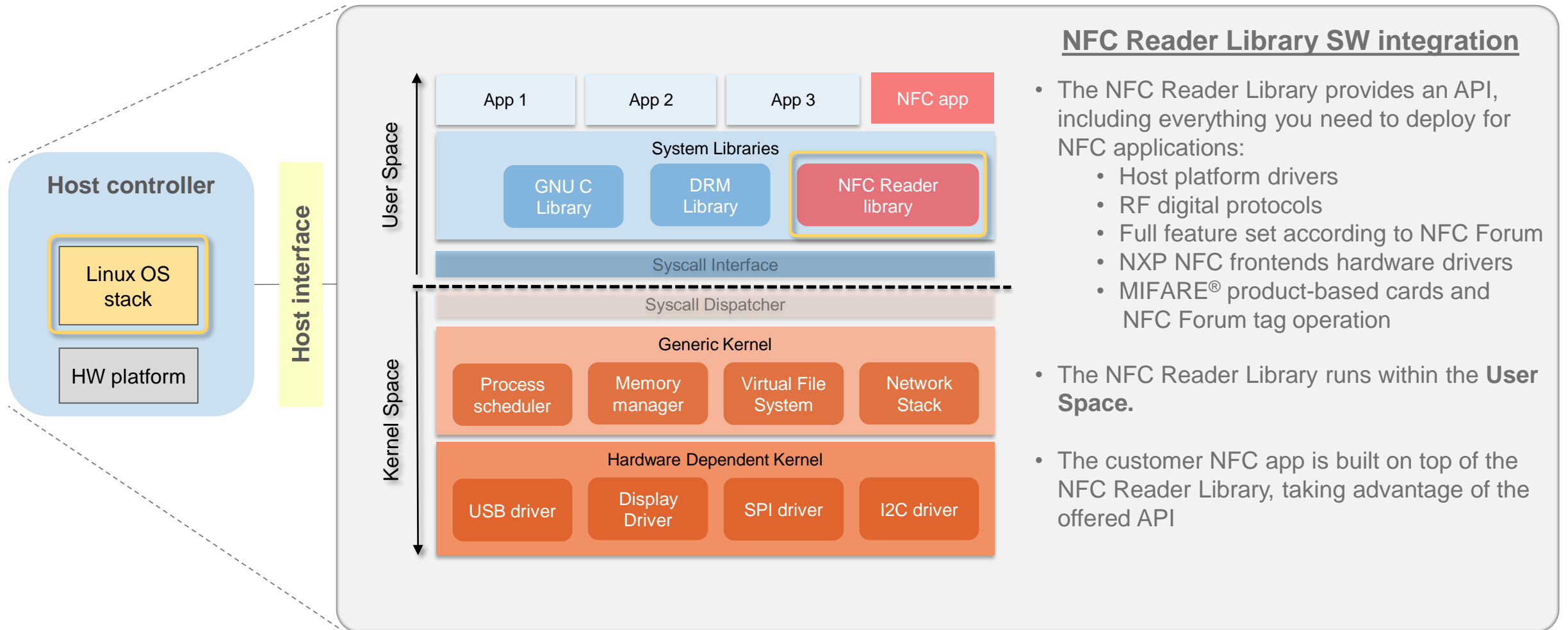
Host controller SW: Linux OS architecture – System call interface



Integrating the NFC Reader Library in Linux



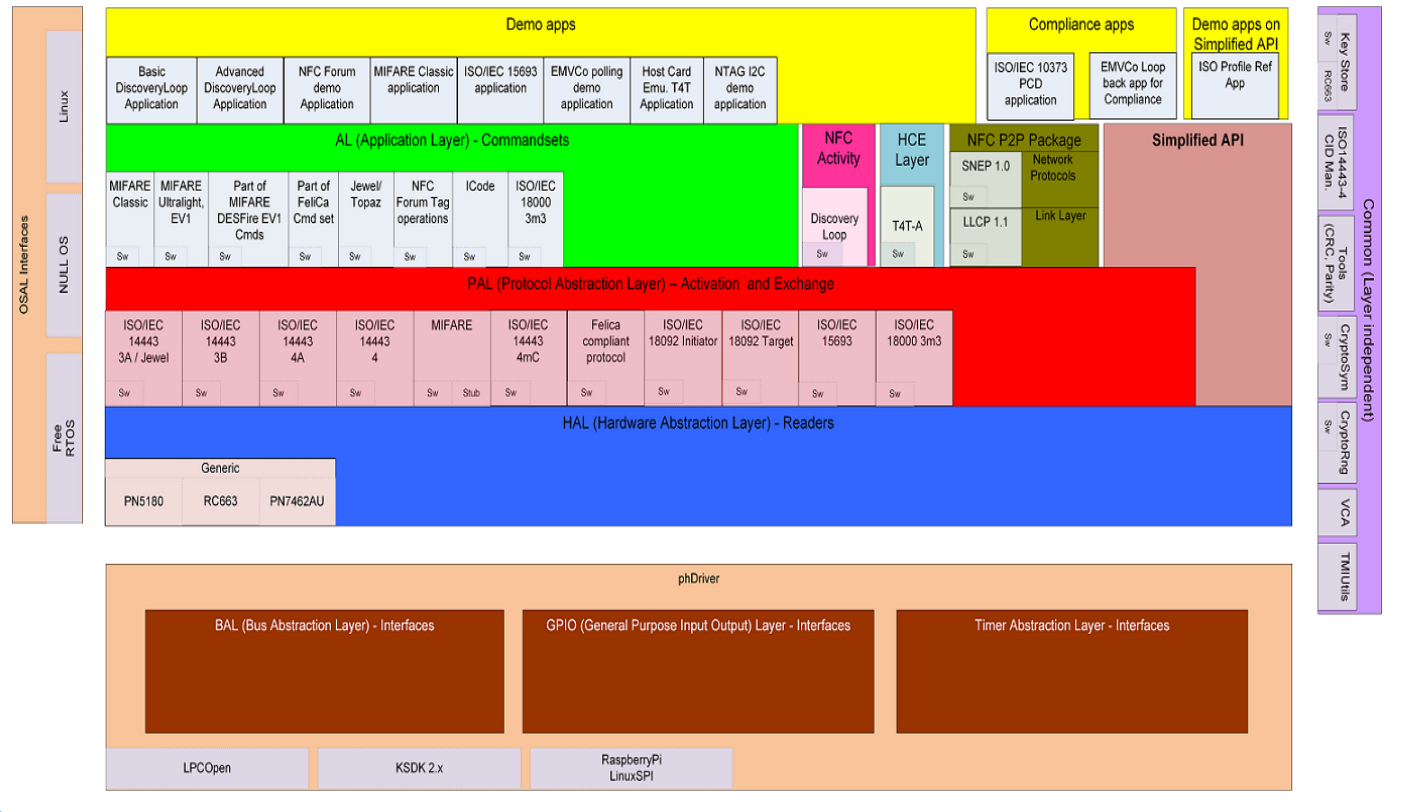
NFC Reader Library: The SW stack for developing NFC applications



The NFC Reader Library is the NXP software stack to develop NFC applications and there is an existing version for Linux OS architecture!

NFC Reader Library support for multiple products and platforms

NFC Reader Library



Supported products:*

- CLRC663 *plus*
- PN5180
- PN7462AU

Supported dev boards:*

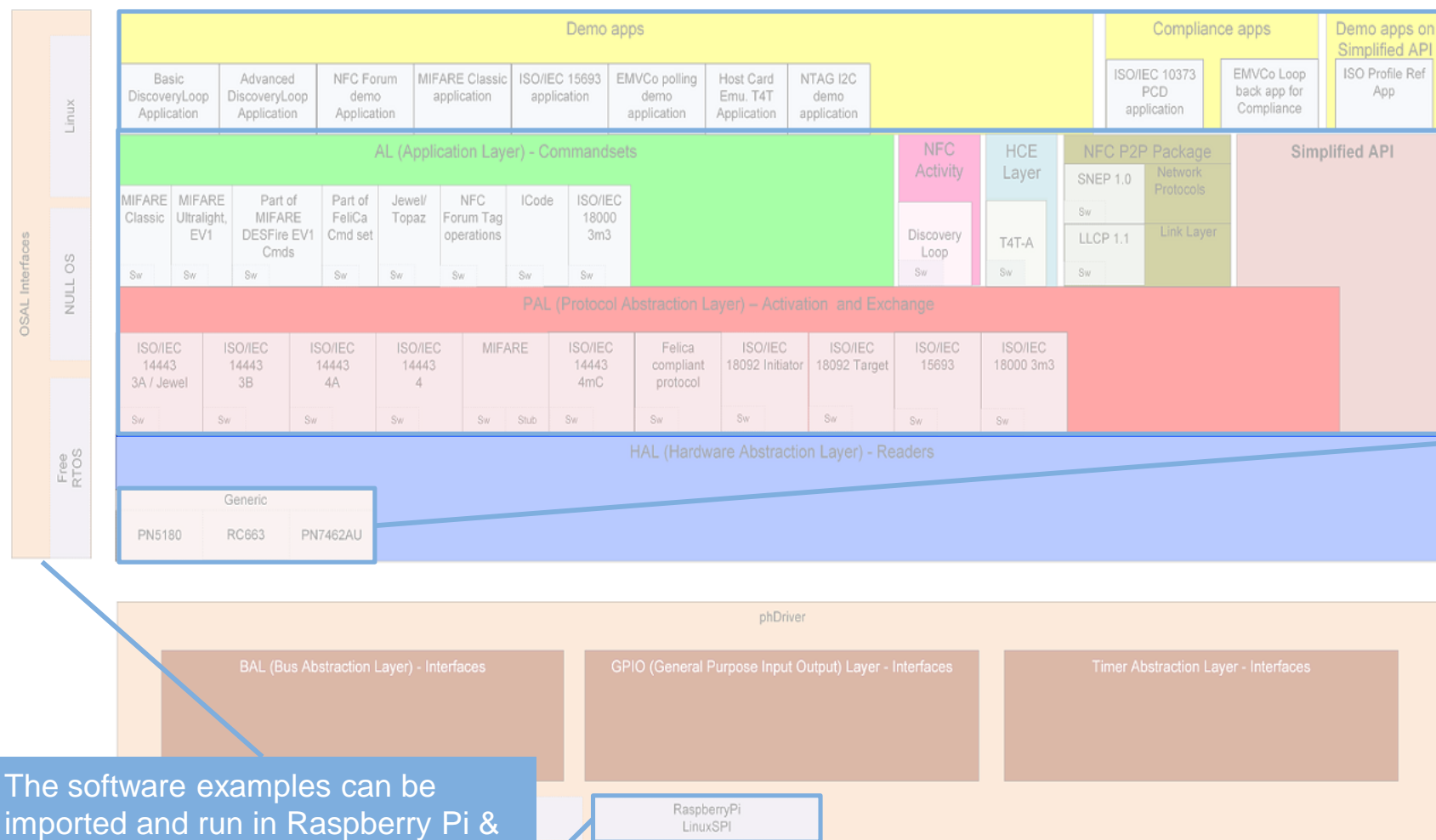
- CLEV6630B
- PNEV5180B
- PNEV7462B

Supported platforms:*

- LPC1769
- FRDM-K82F
- **Raspberry Pi Model 3 → Linux**
- ... and portable to other MCUs and platforms.

Info and more information: www.nxp.com/pages/:NFC-READER-LIBRARY

NFC Reader Library support for Linux



11 software examples available to be tested and re-used in Linux

AL and PAL layers are **hardware and platform independent**, so they can be used in Linux as they are without any adaptation

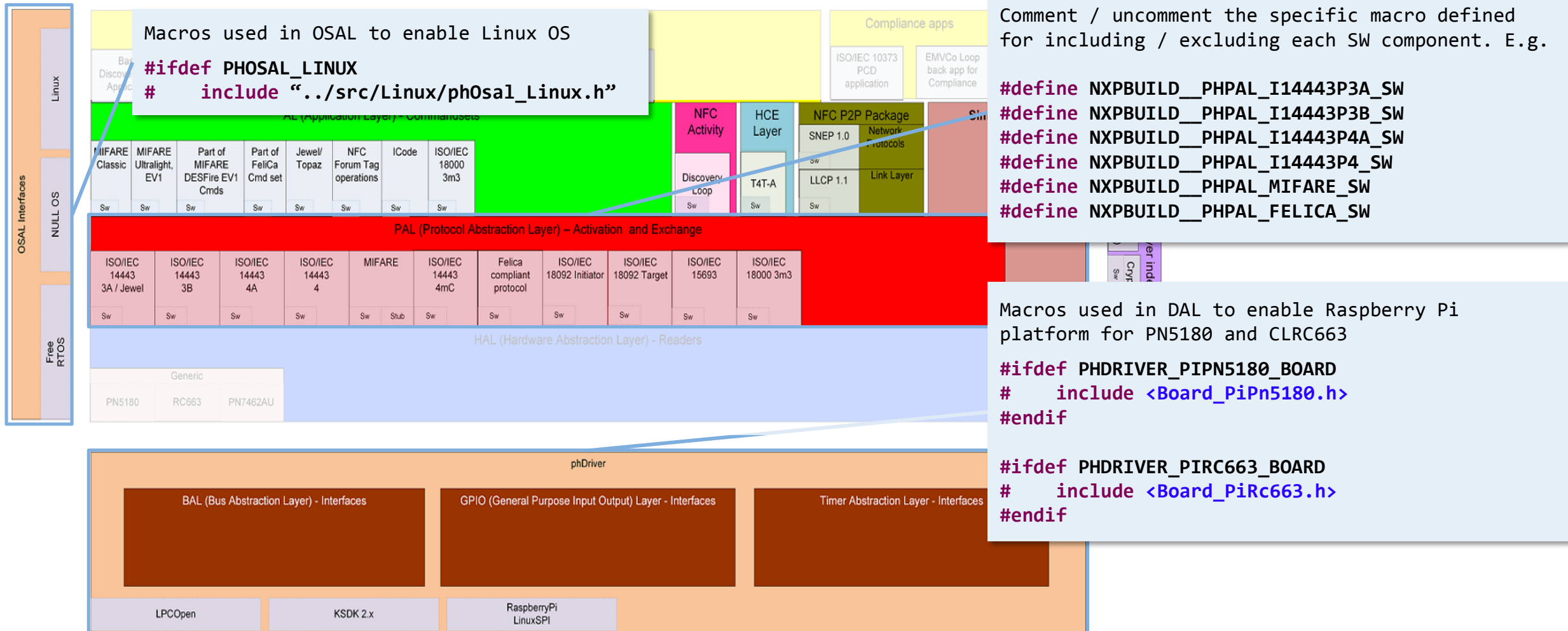
HAL is **platform independent**, so NXP NFC readers can be used in Linux as it is without any adaptation

The software examples can be imported and run in Raspberry Pi & Linux without any adaptation.

Support for other platforms requires adaptations in OSAL and DAL.



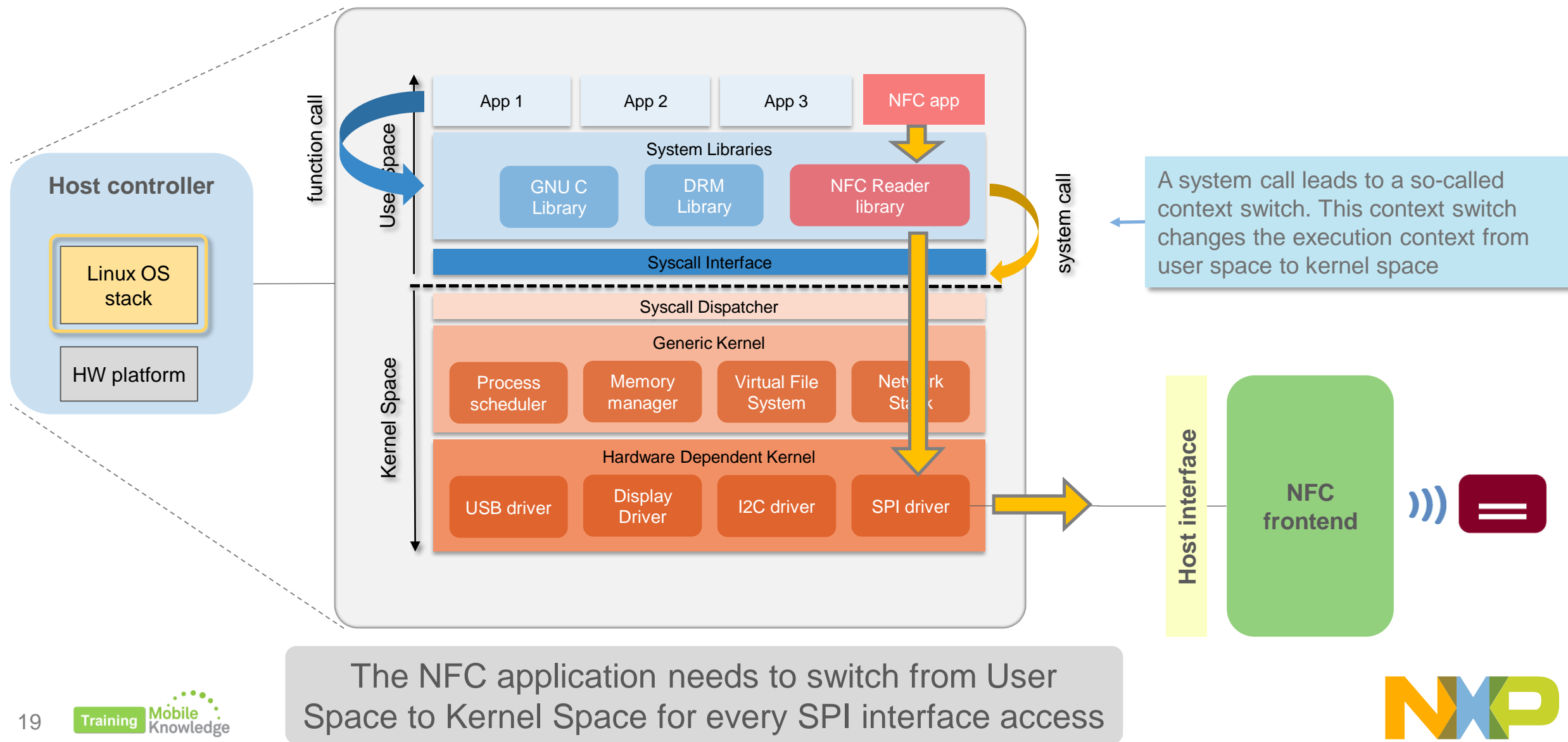
NFC Reader Library - building the SW stack for Linux



Host interface access on Linux systems

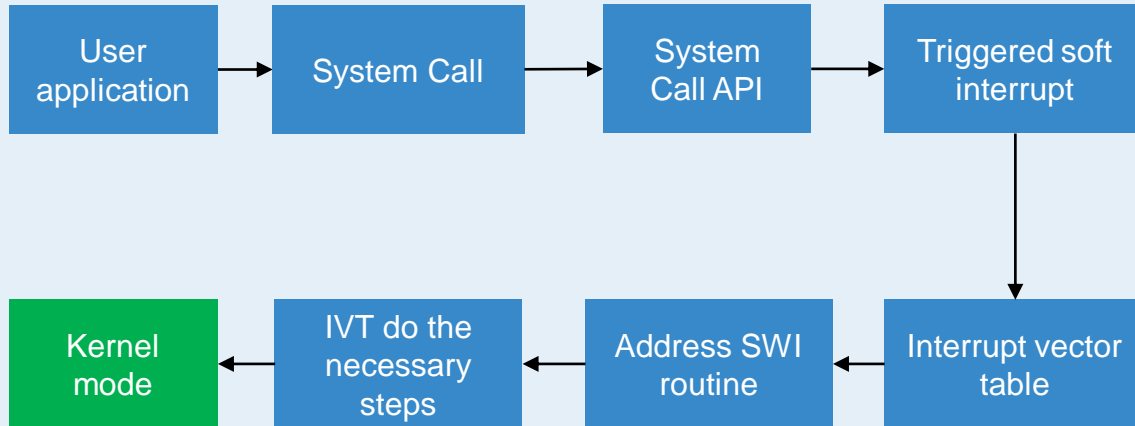


Linux based application: System call interface



Transition between User mode and Kernel mode

Switching from User mode to Kernel mode



- User application initiates switching to kernel mode making a system call (e.g. open, read, write, etc)
- A software interrupt (SWI) is triggered
- The interrupt vector table launches the handler routine which performs all the required steps to switch the user application to kernel mode
- Start execution of kernel instructions on behalf of the user process.

Advantage:

- Well-defined interface.
- Horizontal separation: Avoids a crashing application crashing the whole system and protects system resources.

Disadvantage:

- Performance degradation: A system call is much **slower** than a direct function call



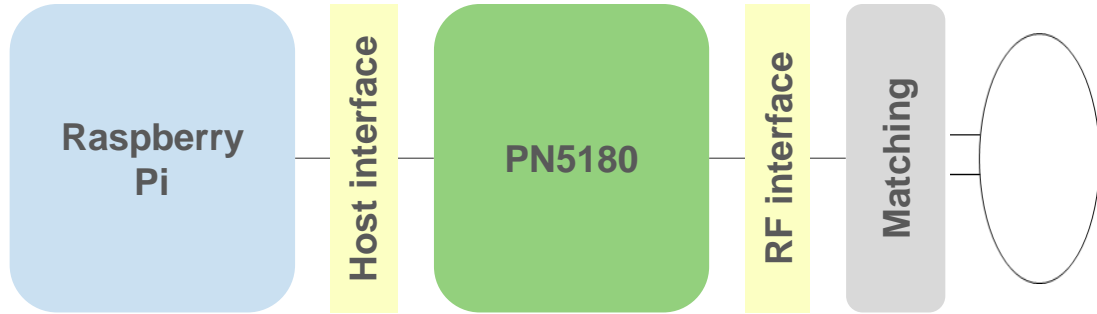
Could challenge the design of time-critical NFC applications

Latency analysis: Linux vs bare metal



Hardware setup

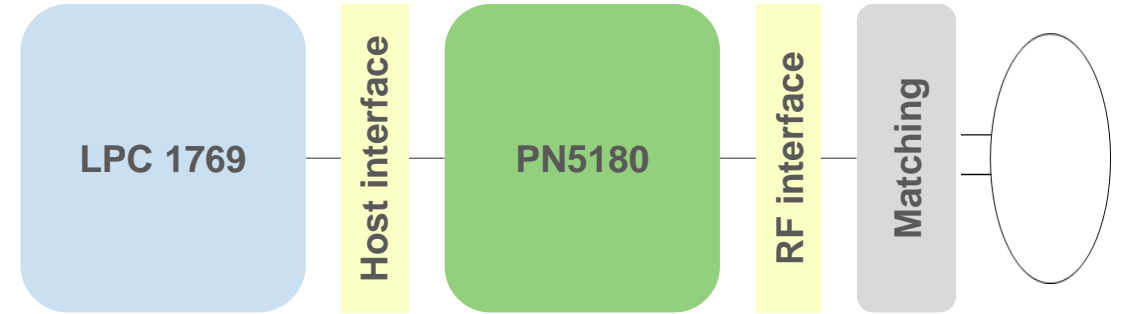
Linux setup



Linux hardware platform

- Raspberry Pi 3 Model B
 - 1.2 GHz 64-bit quad-core ARMv8 CPU
 - ❖ Limited to 1 Core @ 100 MHz (3 cores disabled)
 - 1 GB RAM
- PNEV5180B (with LPC bypassed)
 - SPI host interface

Bare metal setup

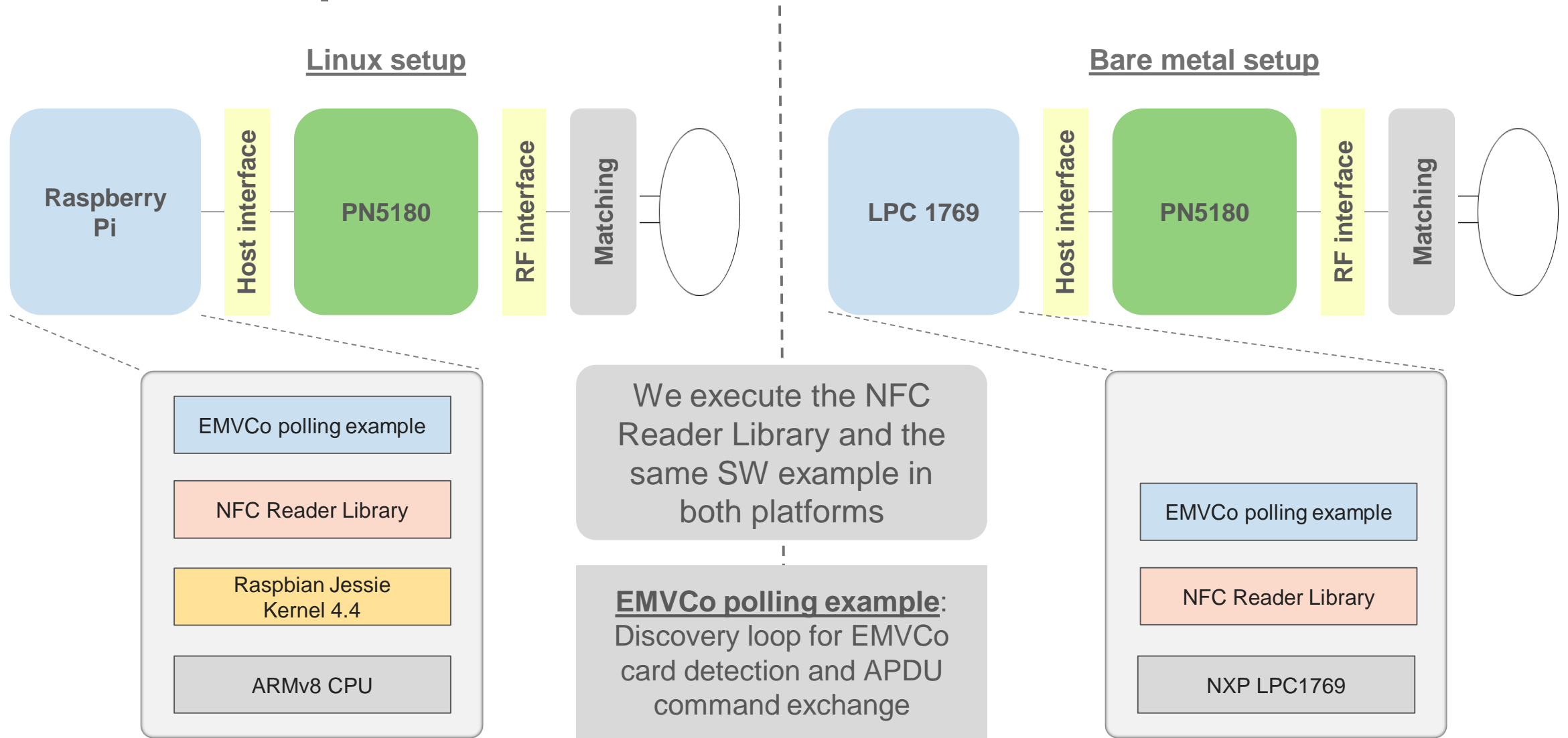


Bare metal hardware platform

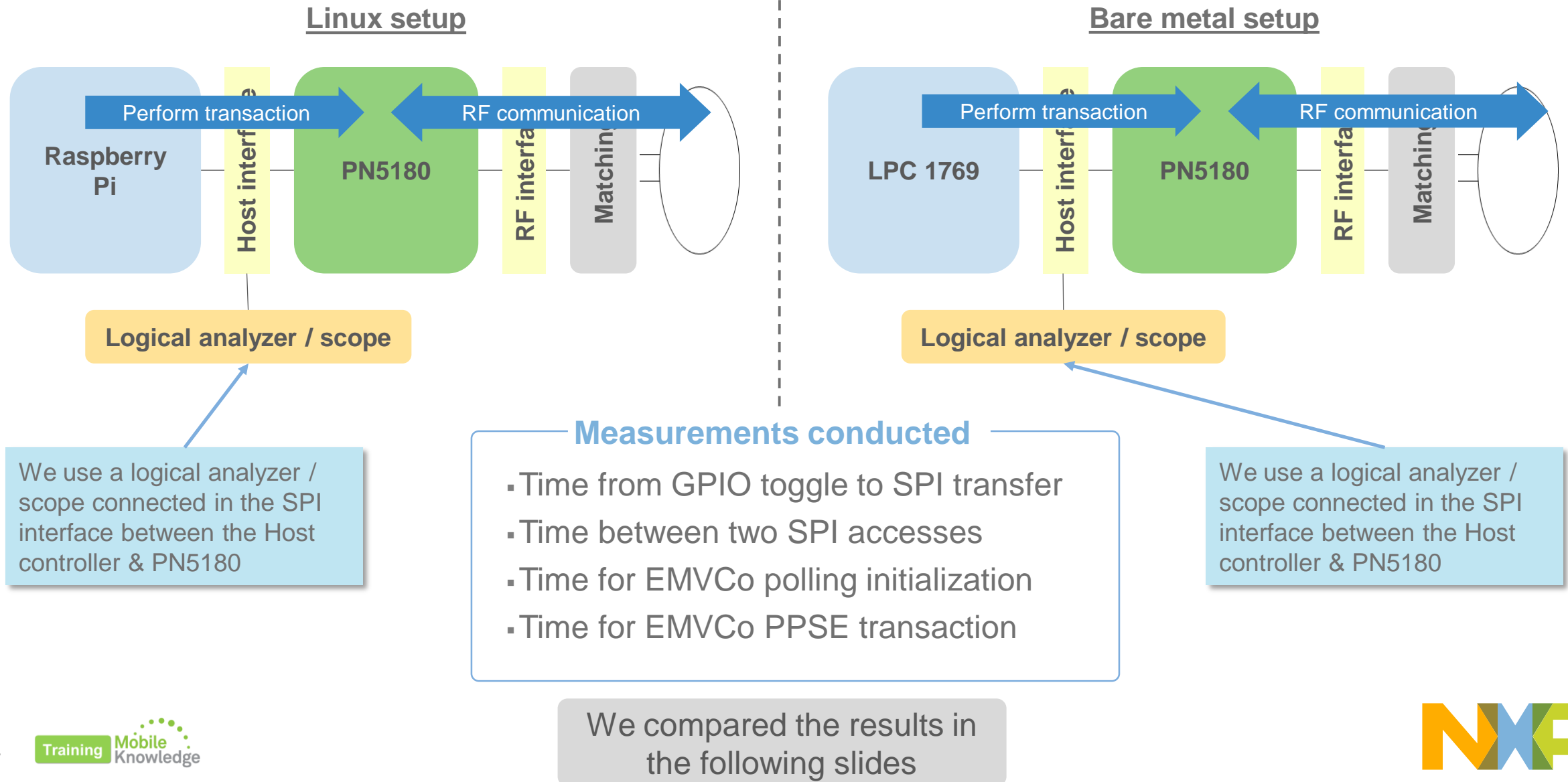
- NXP LPC1769 uC
 - ARM 1 core @ 96 MHz
- LPC-Link2 connected for debugging
- PNEV5180B
 - SPI host interface

We limited Raspberry Pi clock and MCU cores to achieve a comparable setup with LPC1769

Software setup

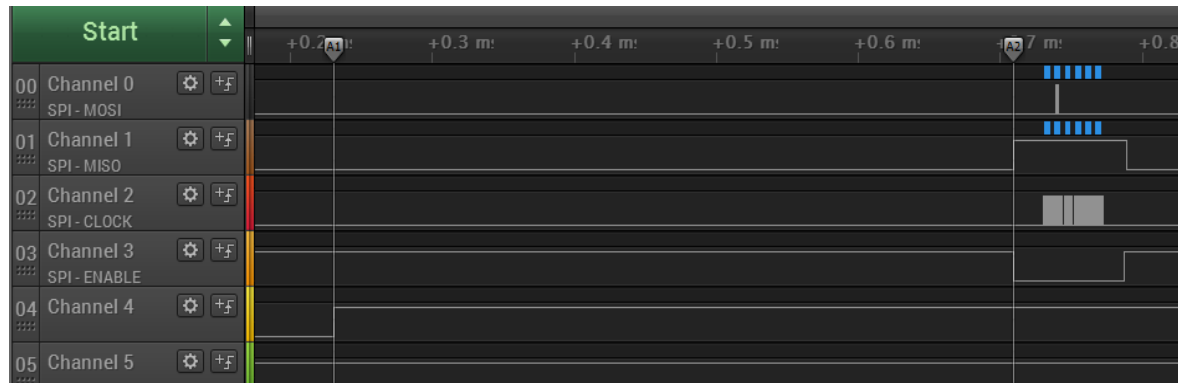


Measurement setup



Measured time from GPIO toggle to SPI transfer

Linux setup



| A1 - A2 | = 0.47875 ms

A1 @ 1.48323075 s
A2 @ 1.4837095 s

Until we start writing into the SPI interface, it takes **0.478 ms**

```
1. Set_GPIO(High)*;  
2. phhalHw_PN5180_WriteRegister(...);  
3. Set_GPIO(Low);
```

* Pseudo-code extracted from the real EMVCo polling source code example from the NFC Reader Library

* GPIO toggling execution takes less than 350us

Linux setup is ~ 200x times slower than bare metal setup

Bare metal setup



| A1 - A2 | = 2.5 us

A1 @ 1.41213525 s
A2 @ 1.41213775 s

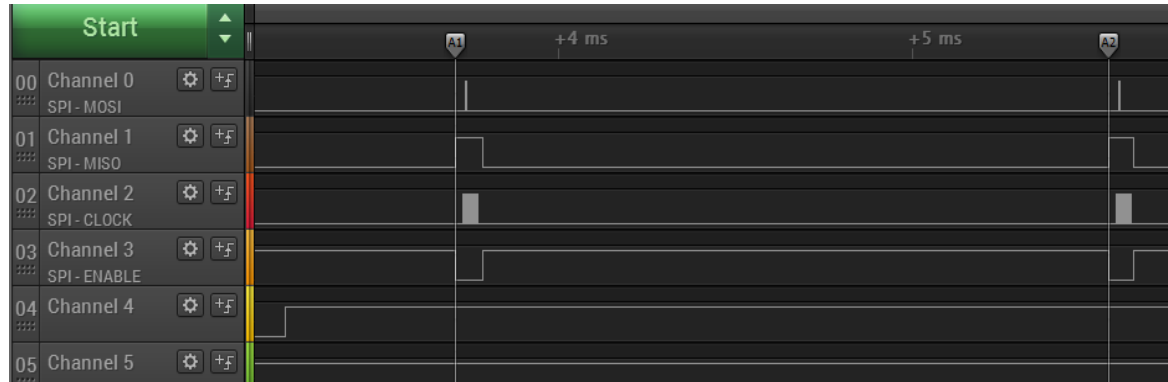
Until we start writing into the SPI interface, it takes **2.5 us**

```
1. Set_GPIO(High)*;  
2. phhalHw_PN5180_WriteRegister(...);  
3. Set_GPIO(Low);
```

* GPIO toggling execution takes less than 3us

Measured time between two SPI accesses

Linux setup



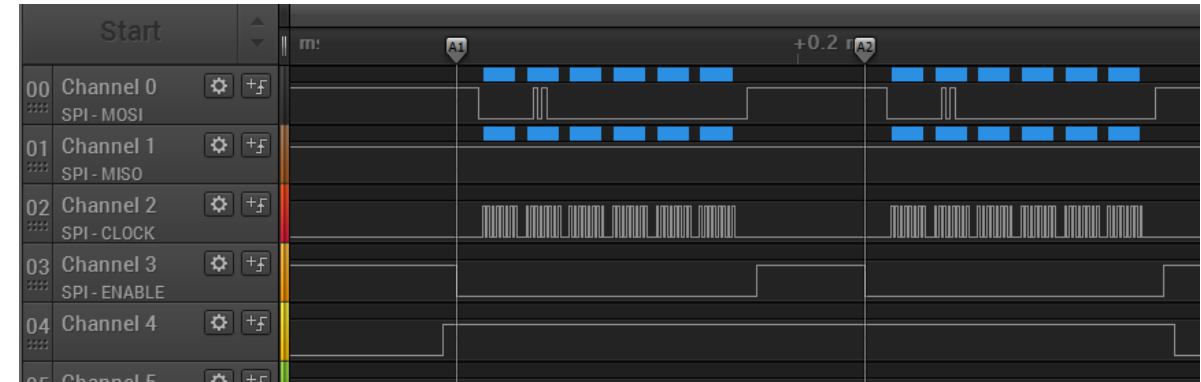
| A1 - A2 | = 1.841375 ms

A1 @ 1.4837095 s
A2 @ 1.48550875 s

it takes **1.8 ms** until we start writing the second SPI transfer.

```
1. Set_GPIO(High)*;  
2. phhalHw_PN5180_WriteRegister(...);  
3. phhalHw_PN5180_WriteRegister(...);  
4. Set_GPIO(Low);
```

Bare metal setup



| A1 - A2 | = 74.5 μs

A1 @ 1.41213775 s
A2 @ 1.41221225 s

It takes **74.5us** until we start writing the second SPI transfer.

```
1. Set_GPIO(High)*;  
2. phhalHw_PN5180_WriteRegister(...);  
3. phhalHw_PN5180_WriteRegister(...);  
4. Set_GPIO(Low);
```

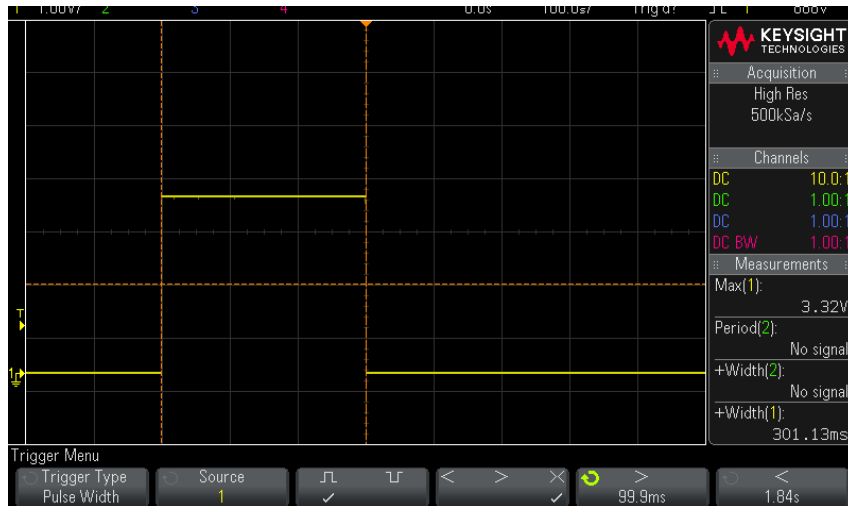
* Pseudo-code extracted from the real EMVCo polling source code example from the NFC Reader Library

Linux setup is ~ 25x times slower than bare metal setup



Measured time for EMVCo polling initialization

Linux setup

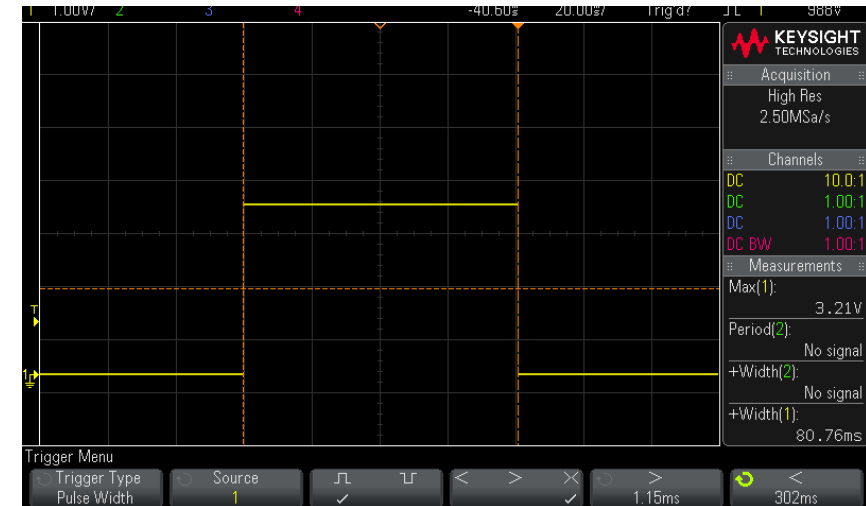


+Width(1):
301.13ms

Measured time for 10
EMVCo polling inits.
1 init ~30.1ms

Linux setup is ~ 4x times slower
than bare metal setup

Bare metal setup



+Width(1):
80.76ms

Measured time for 10
EMVCo polling inits.
1 init ~8.07 ms

```
void Emvco_Polling(void * pHalParams)
{
    Board_LED_Set(LED_NUM, 1);

    for(i=0;i<10;i++)
    {
        /* Load Emvco Default setting */
        status = LoadEmvcoSettings();
        CHECK_STATUS(status);

        /* Perform RF Reset */
        status = EmvcoRfReset();
        CHECK_STATUS(status);

        status = phalHw_SetConfig(pHal, PHAL_HW_CONFIG_SET_EMD, PH_OFF);
        CHECK_STATUS(status);
    }

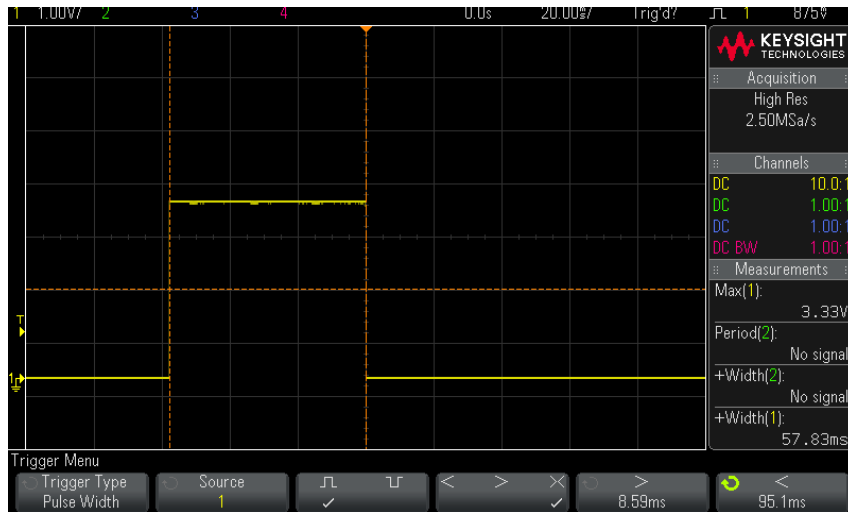
    Board_LED_Set(LED_NUM, 0);
}
```

* During the initialization, several registers are written.
The process is repeated 10 times to get an average



Measured time for EMVCo PPSE

Linux setup

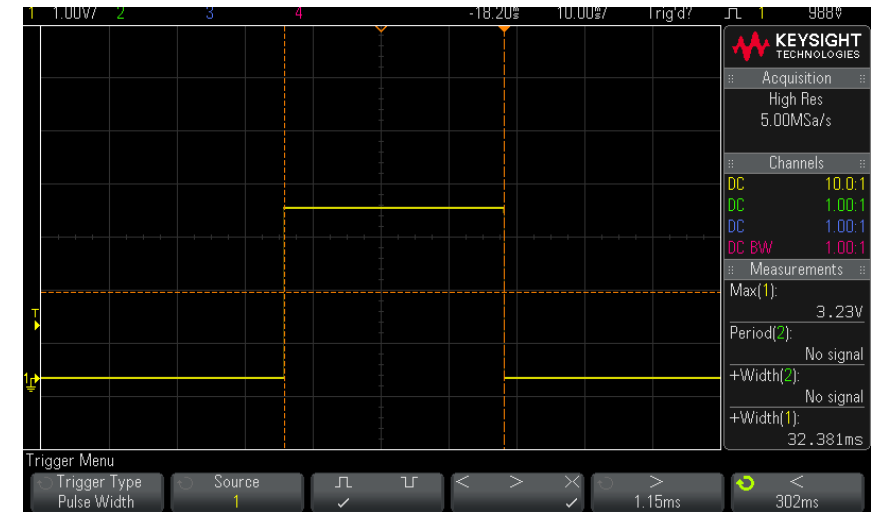


+Width(1):
57.83ms

Measured time for a
EMVCo loopback
transaction takes
57ms

```
*phStatus EMVCoDataLoopBack(...) {  
1. Set_GPIO(High);  
2. EMVCoDataExchange(...);  
3. Set_GPIO(Low);  
}
```

Bare metal setup



+Width(1):
32.381ms

Measured time for a
EMVCo loopback
transaction takes
32ms

Linux setup is ~ 2x times slower
than bare metal setup

* Pseudo-code extracted from the real
EMVCo polling source code example from
the NFC Reader Library

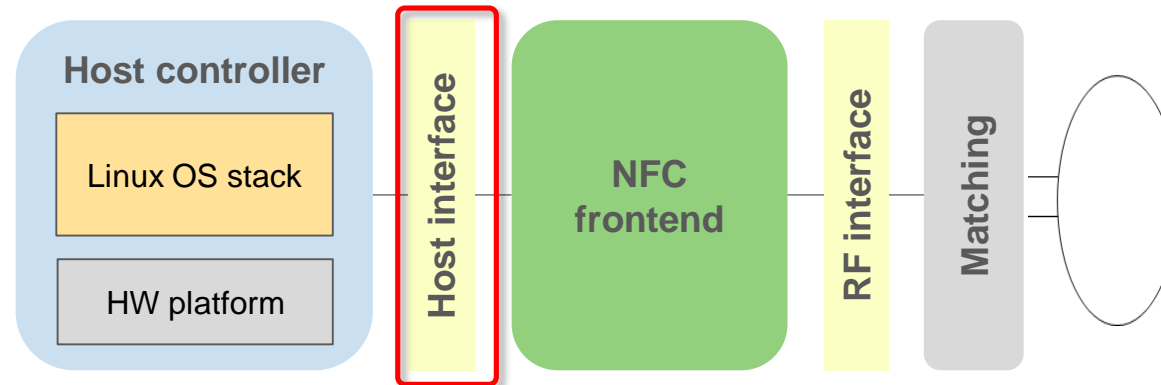


Overcoming Linux higher latency for time-sensitive applications



Recommendations to reduce Linux latency

Linux-based NFC reader architecture



- **High latency:** Access the SPI driver in Kernel space is slow.
- **High CPU load:** There is a lot of code involved just to write one register.

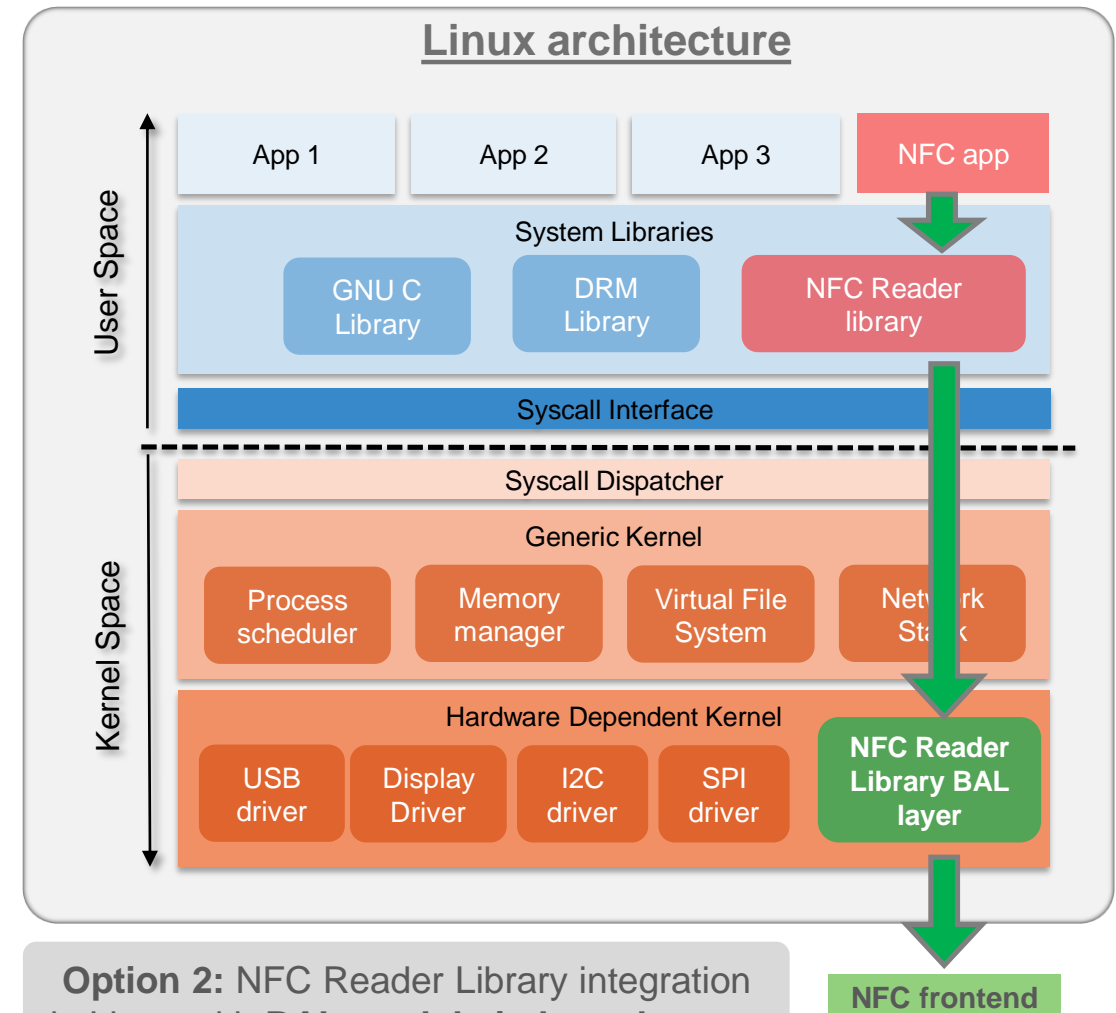
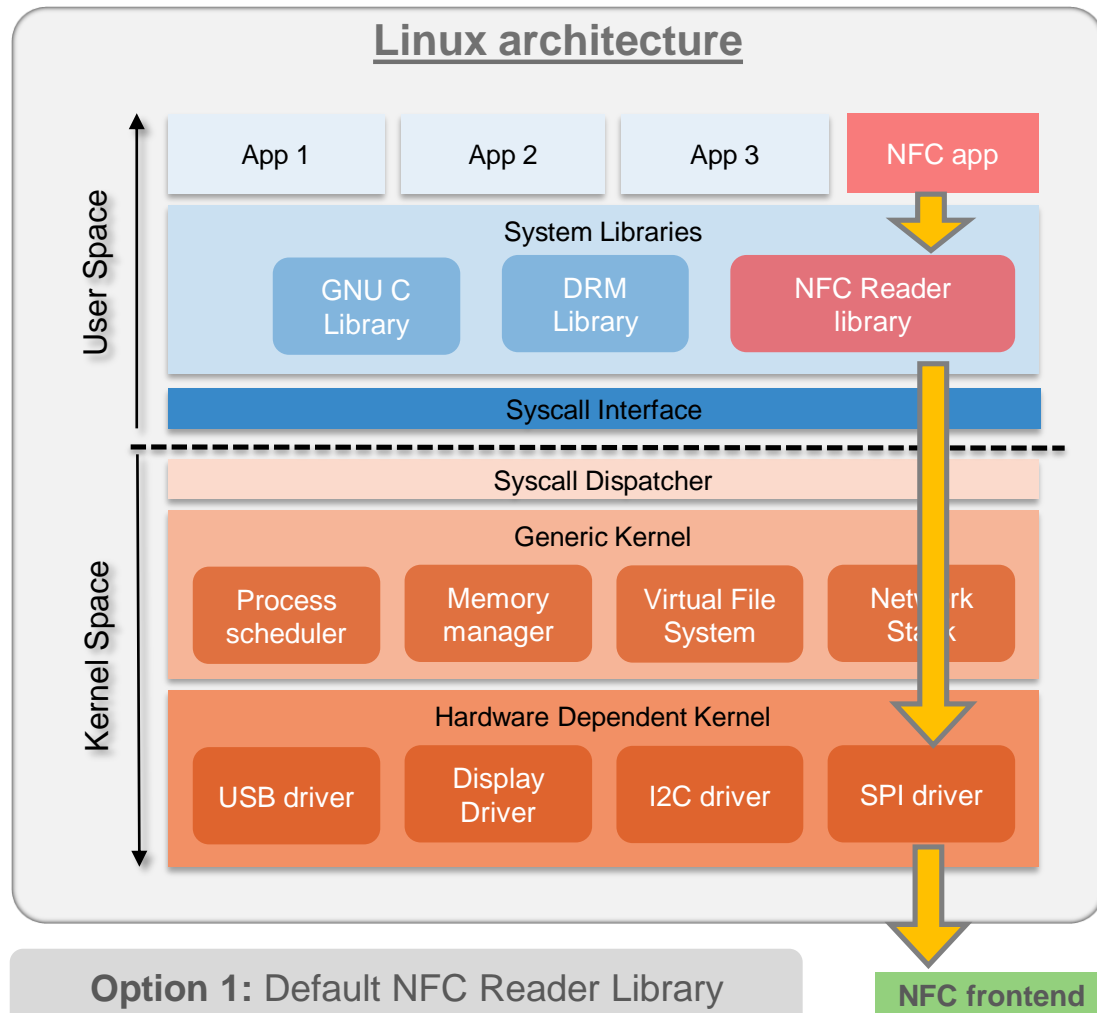
Solutions

- Increase CPU/SPI clock as much as the MCU can process.
- Reduce SPI / host interface interactions as much as possible: Linux driver is optimized for few long transactions rather than lots of short ones

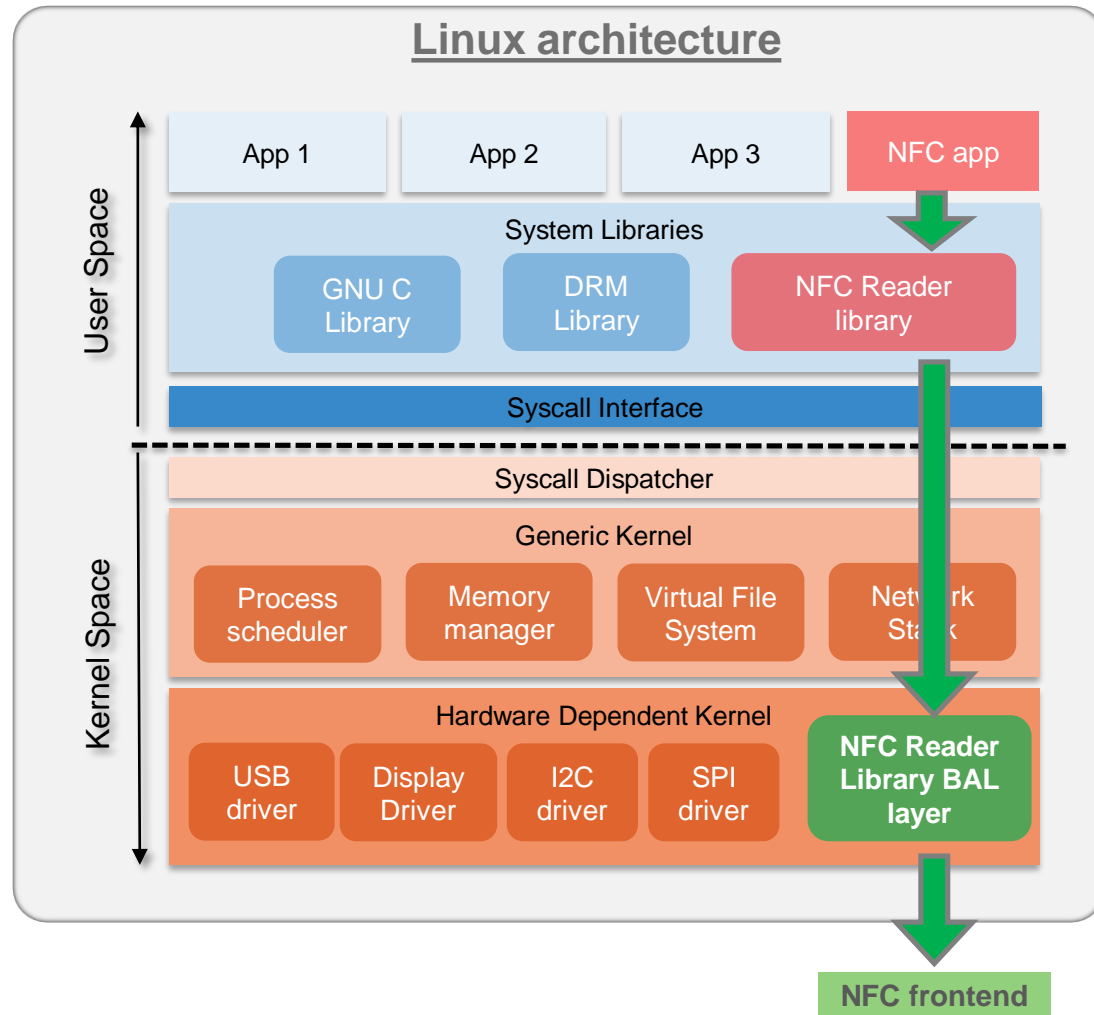
The most effective solution!!

- **Move NFC Reader Library BAL module to Kernel space**

NFC Reader Library support of BAL module in Kernel space



NFC Reader Library BAL module: User Space vs Kernel space



BAL layer in User Space

1. Read GPIO to wait for BUSY line from previous command going low.
2. Setup and start first SPI transfer.
3. Read GPIO to wait for BUSY going low.
4. Setup and start second SPI transfer.
5.

Plenty of system calls and context switching operations

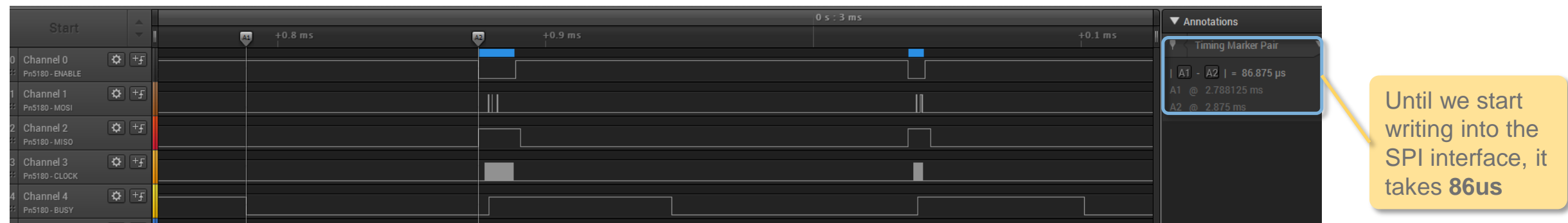
BAL layer in Kernel Space

1. System call read() leading to a context switch
2. Access BAL kernel module with direct access to the SPI and GPIO frameworks.

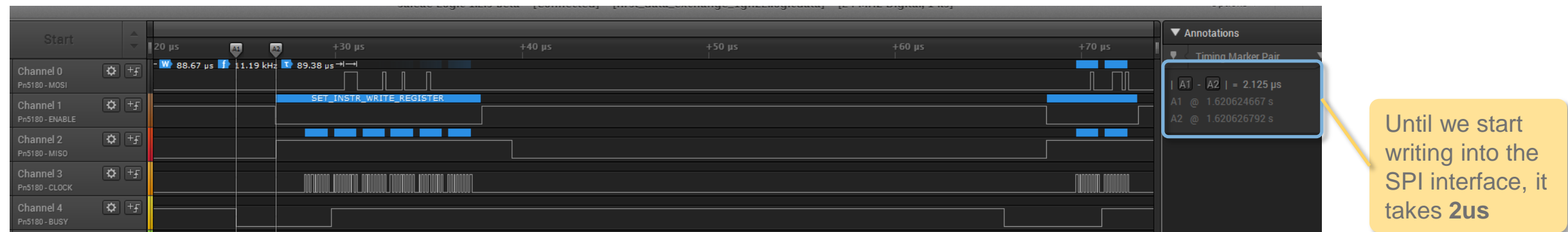
ONLY ONE SYSTEM CALL → Much more efficient, instead of having individual access from user space

NFC Reader Library BAL module: User Space vs Kernel space

BAL layer in User Space: Measured time between two SPI transfers (Raspberry Pi 2 running Linux OS*)



BAL layer in Kernel Space: Measured time between two SPI transfers (Raspberry Pi 2 running Linux OS*)

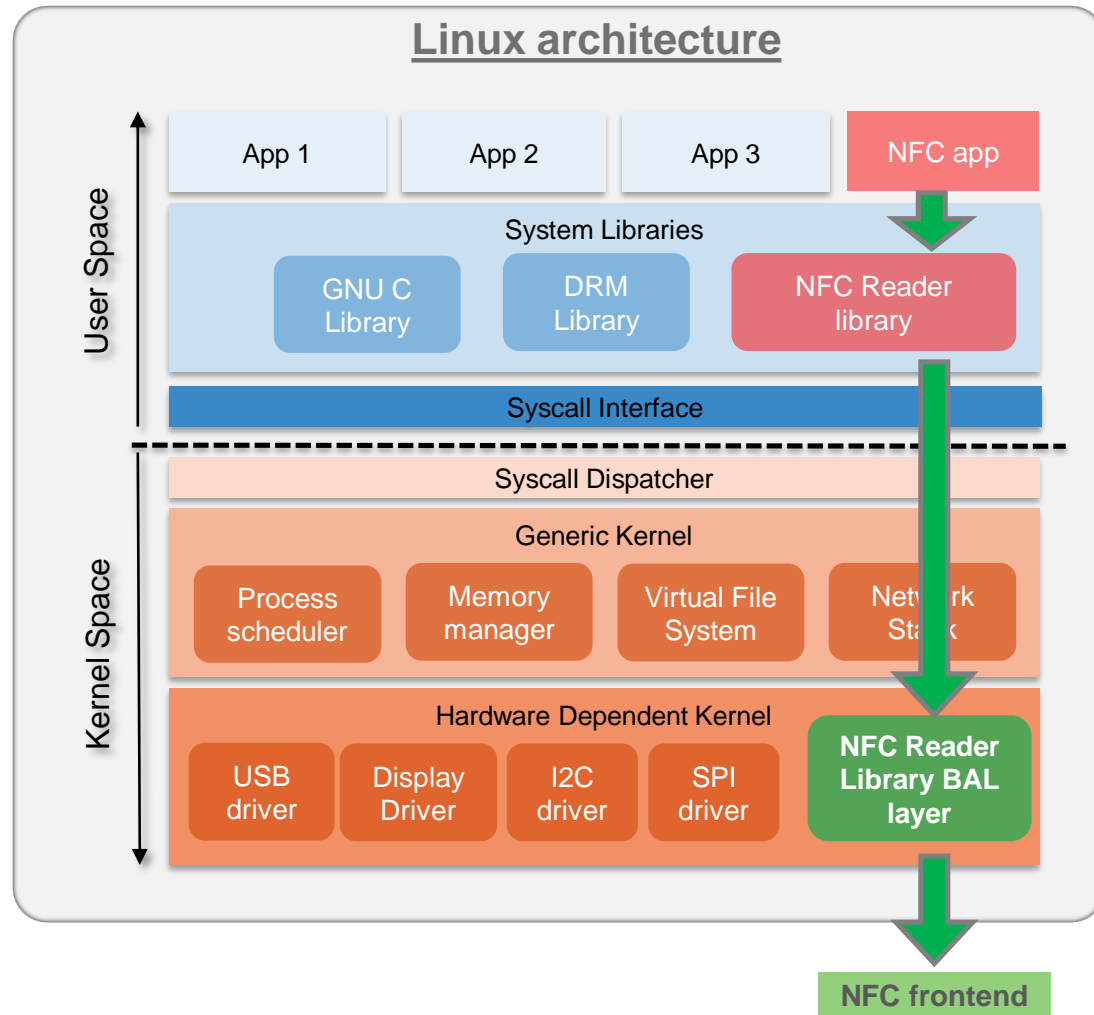


*This setup was conducted with Raspberry Pi 2, 1GHz Quad core Cortex-A7 at full power. Measurements are not comparable with the above sections.

BAL in Kernel space is ~ 40x times faster



NFC Reader Library BAL module in Kernel space: Resources



[1] GitHub repo with:

- Information about building, configuring and loading the module
- An example of the integration on Raspberry Pi.

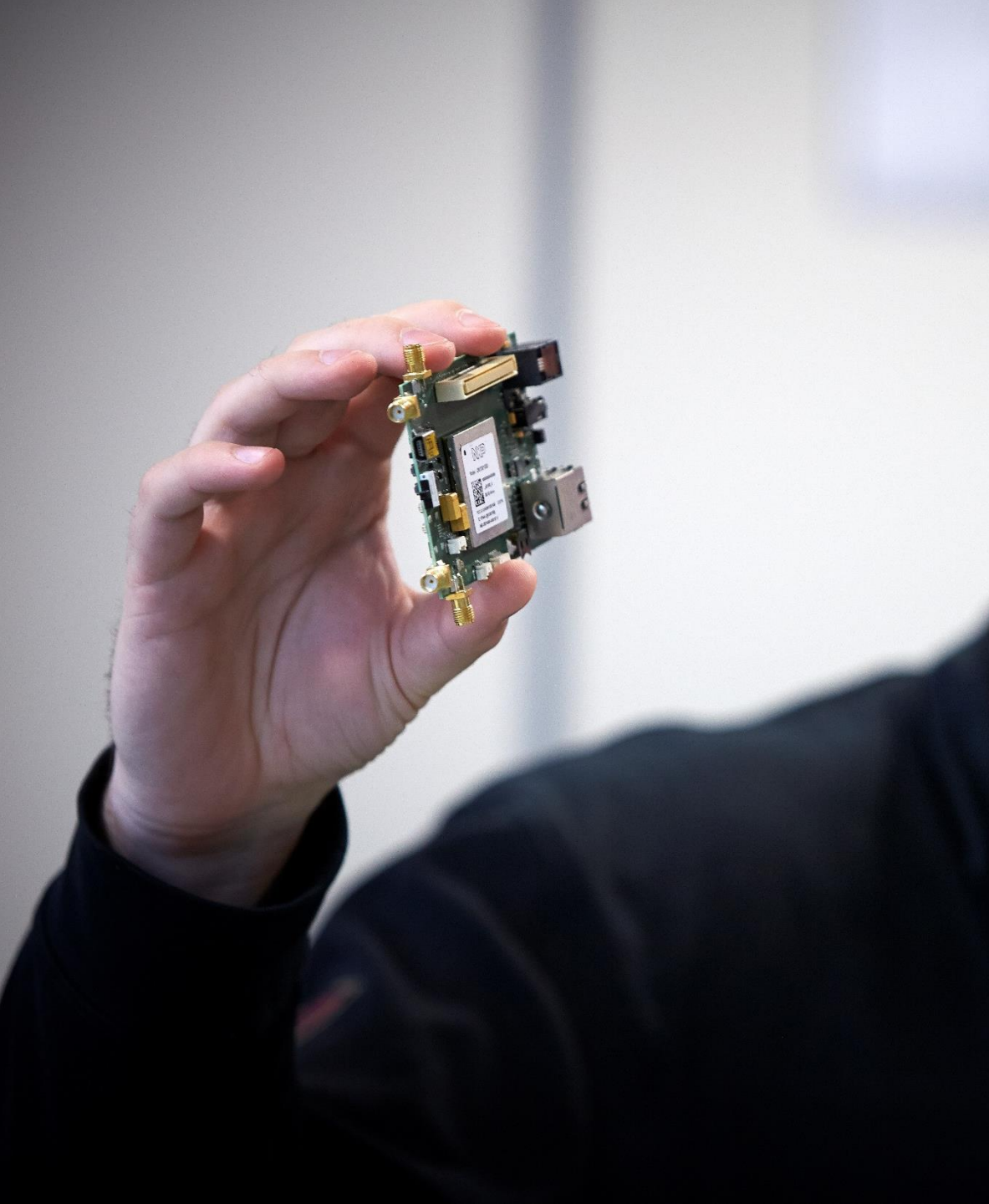
[2] App note with:

- Explanation of how the NFC Reader Library needs to be changed in order to call the kernel module instead of using the default BAL module running in user-space.

[1] <https://github.com/NXPnFCLinux/nxprdlb-kernel-bal>

[2] http://www.nxp.com/documents/application_note/AN11802.pdf

Wrap up & Q&A



Reference links & info

- NFC Reader Library
www.nxp.com/pages/:NFC-READER-LIBRARY
- CLRC663 *plus*
www.nxp.com/products/:CLRC66303HN
- PN5180
www.nxp.com/products/:PN5180
- Github Repo:
<https://github.com/NXPnfcLinux/nxprdlib-kernel-bal>
- NFC Reader Library for Linux installation guidelines
http://www.nxp.com/documents/application_note/A_N11802.pdf

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Embedded software for MCUs

JCOP, Java Card operating Systems

Hardware design and development

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Wireless communications WiFi, ZigBee, Bluetooth, BLE

Contactless antenna RF design, evaluation and testing

MIFARE® product-based applications

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EMVco applications

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GlobalPlatform compliant backend solutions

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How to integrate NFC frontends in Linux

Jordi Jofre (Speaker)

Angela Gemio (Host)

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